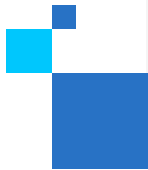


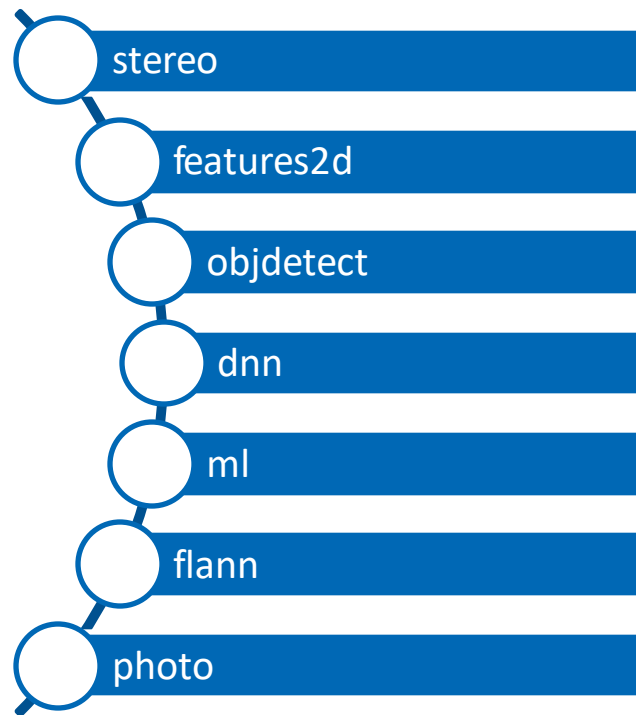
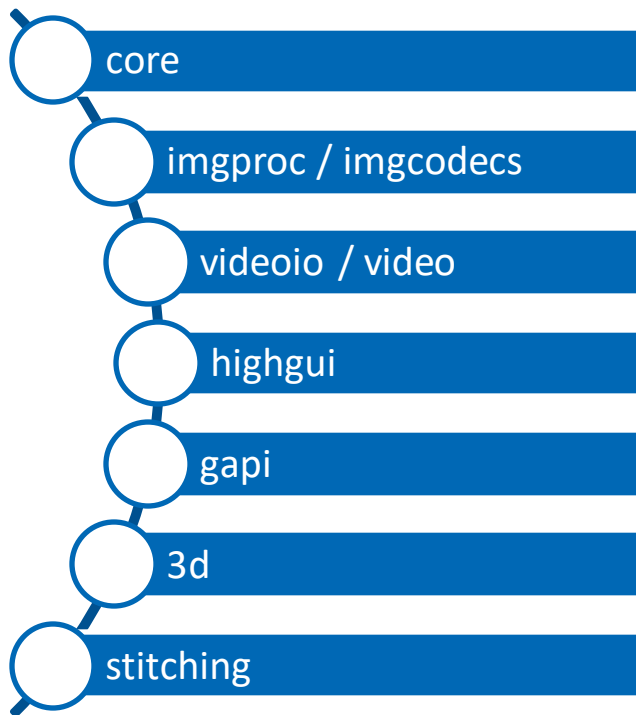
Курс лекций по компьютерному зрению

Введение в библиотеку OpenCV: Модуль DNN

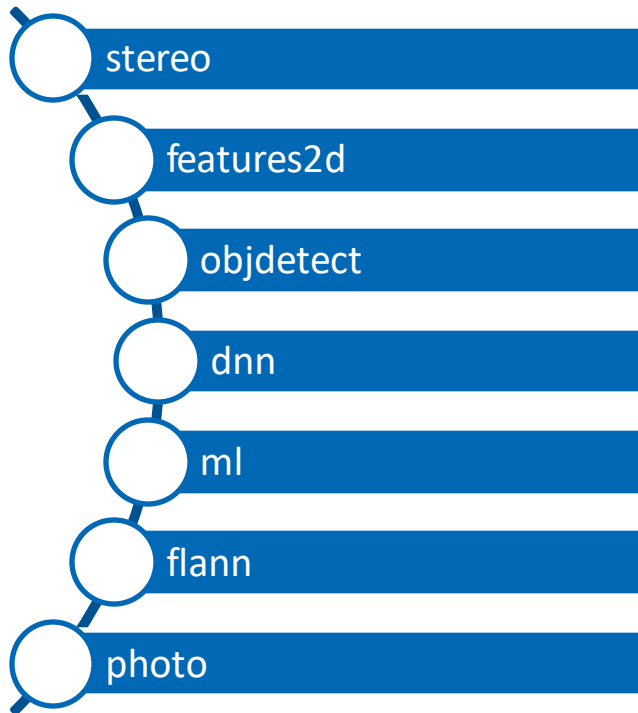
Нестеров Александр, AI Frameworks Engineer



Main modules



Main modules



- Поддержка глубоких сверточных нейронных сетей
- OpenVINO модуль



Main structure: Mat

```
cv::Mat A(h, w, CV_8UC3);
```

- Size, step
- Ref counter (=1)
- Data pointer

```
cv::Mat B = A;
```

- Size, step
- Ref counter (=2)
- Same data pointer

```
cv::Mat C=A(roi);
```

- Size of the ROI, same step
- Ref counter (=3)
- Augmented data pointer

RGBRGBRGBRGBRGBRGBRGBRGBRGBRGB
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RGBRGBRGBRGBRGBRGBRGBRGBRGBRGB
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RGBRGBRGBRGBRGBRGBRGBRGBRGBRGB
RGBRGBRGBRGBRGBRGBRGBRGBRGBRGB



Main structure: Mat

cv::Mat C=A(roi);
Size of the ROI, same step
Ref counter (=3)
Augmented data pointer

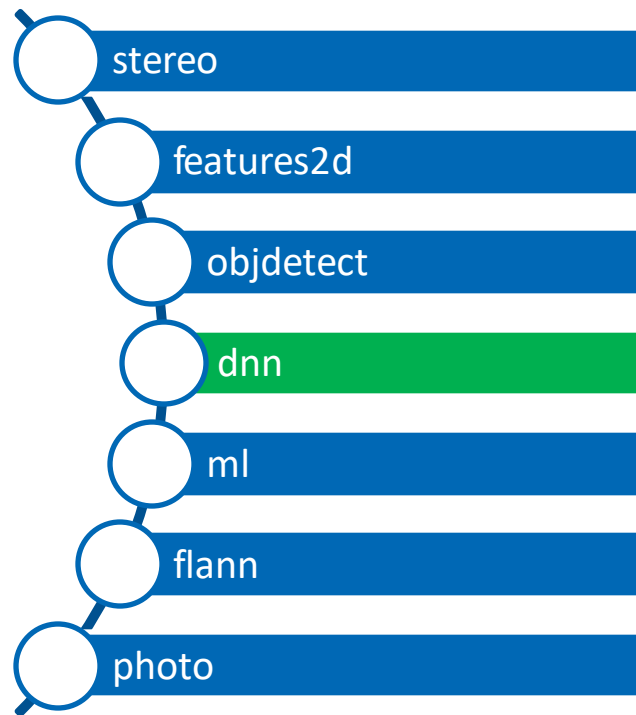
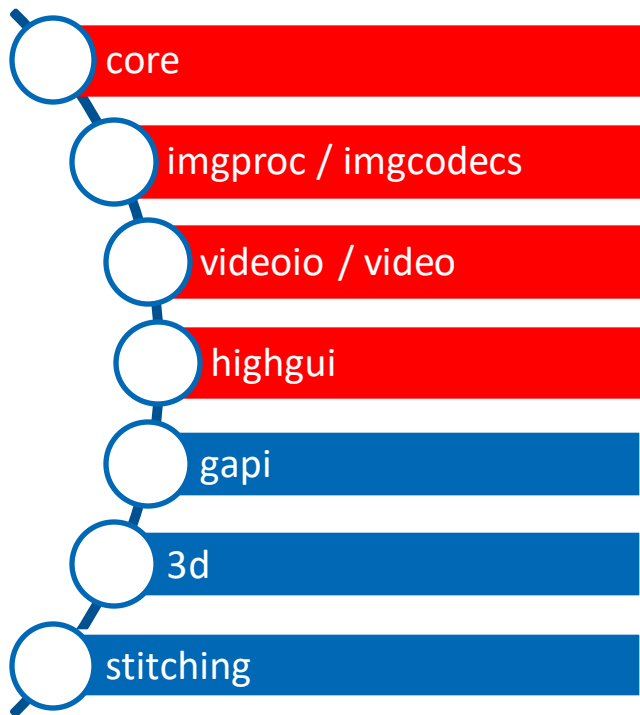


Раскладка памяти матрицы C

RGBR*****RGBR*****
...



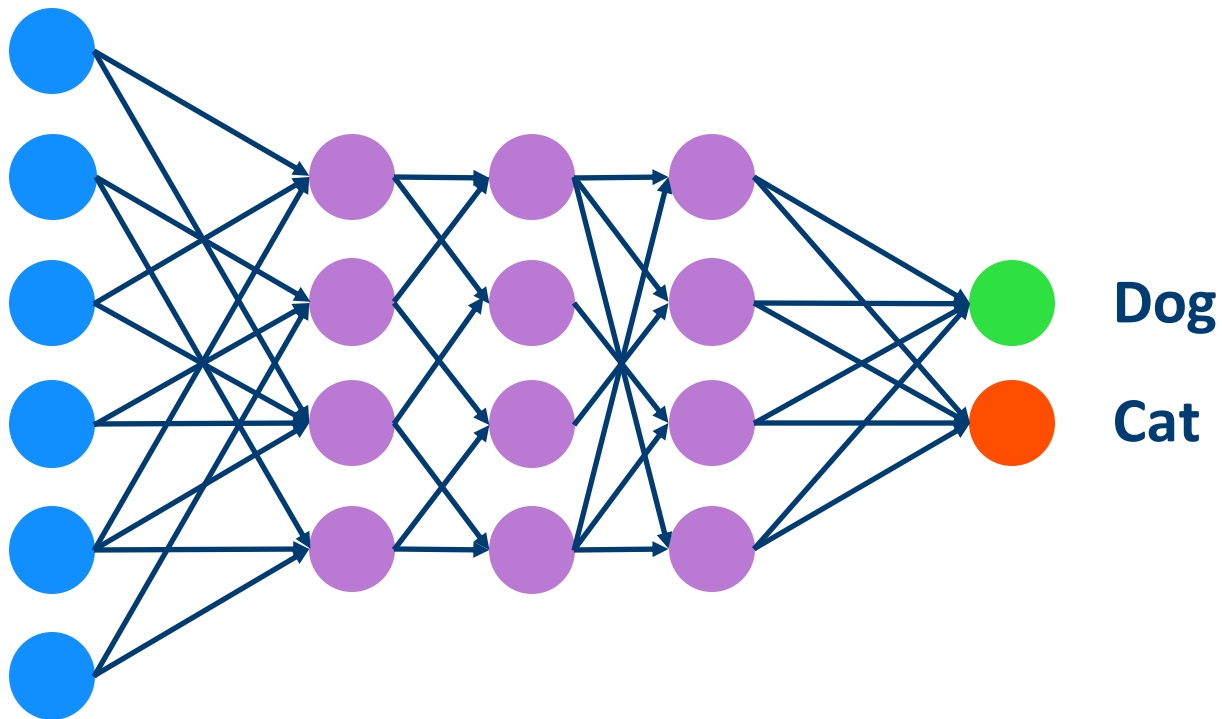
Main modules



https://github.com/learning-process/opencv_practice

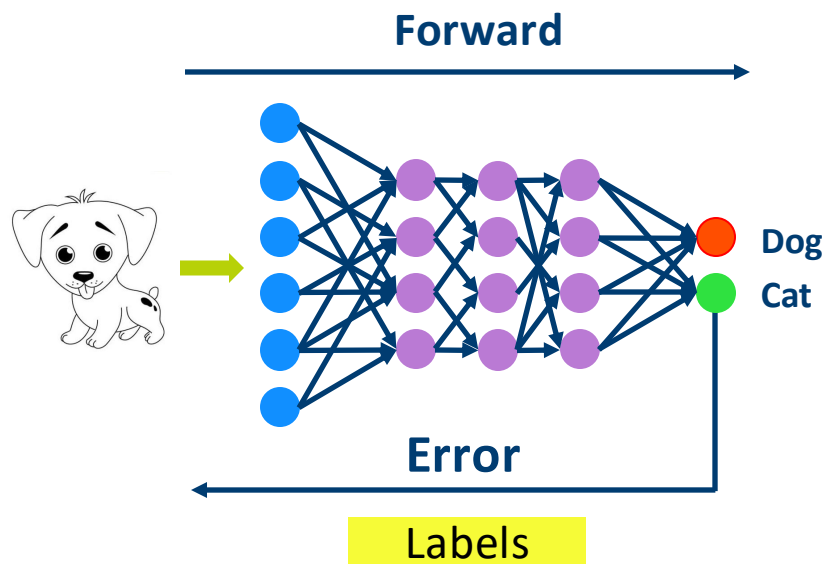


Deep neural network

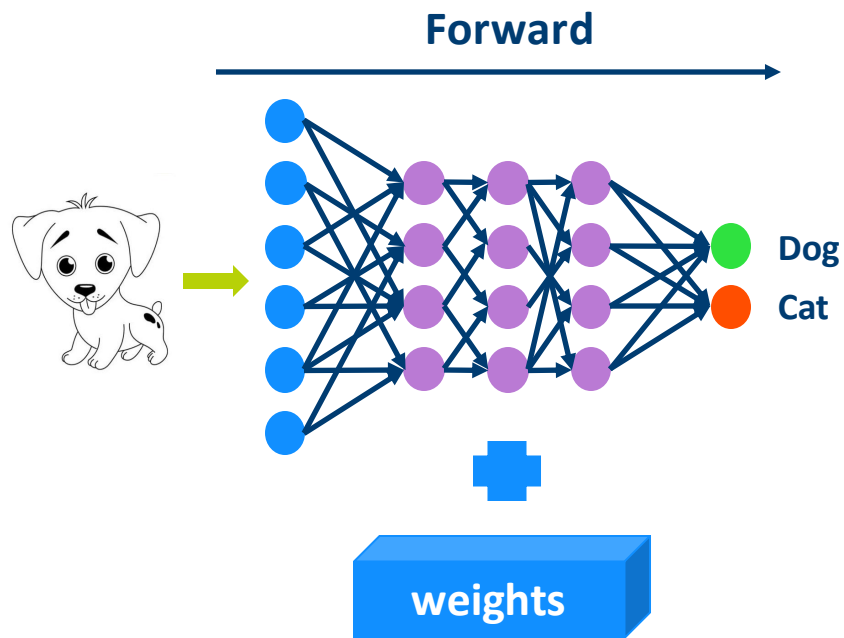


What can be done with DNN?

Learning

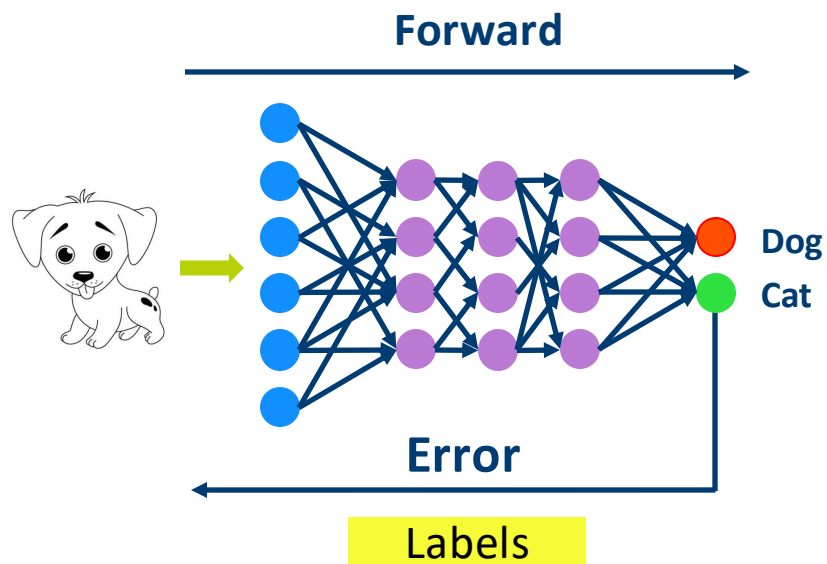


Inference

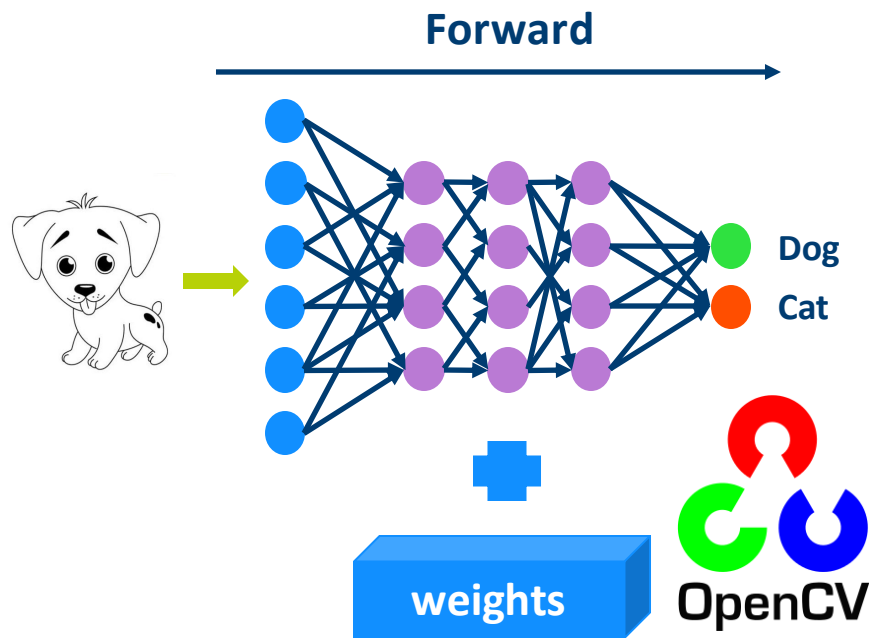


What can be done with DNN?

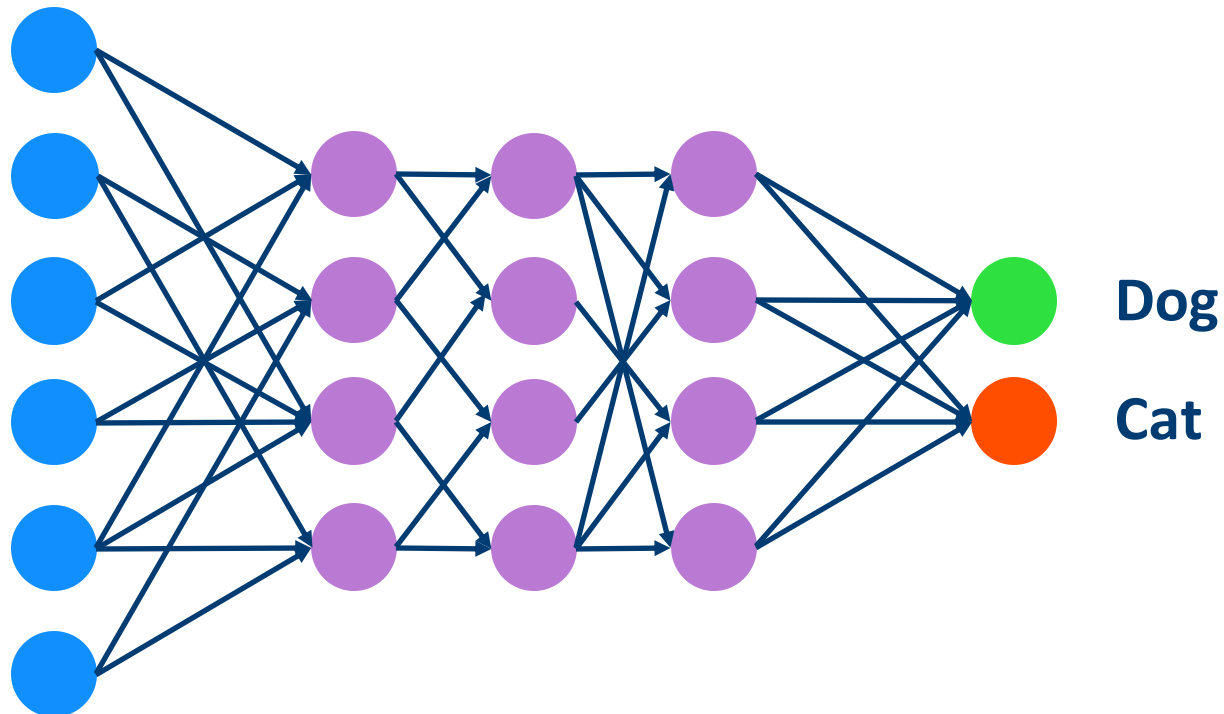
Learning



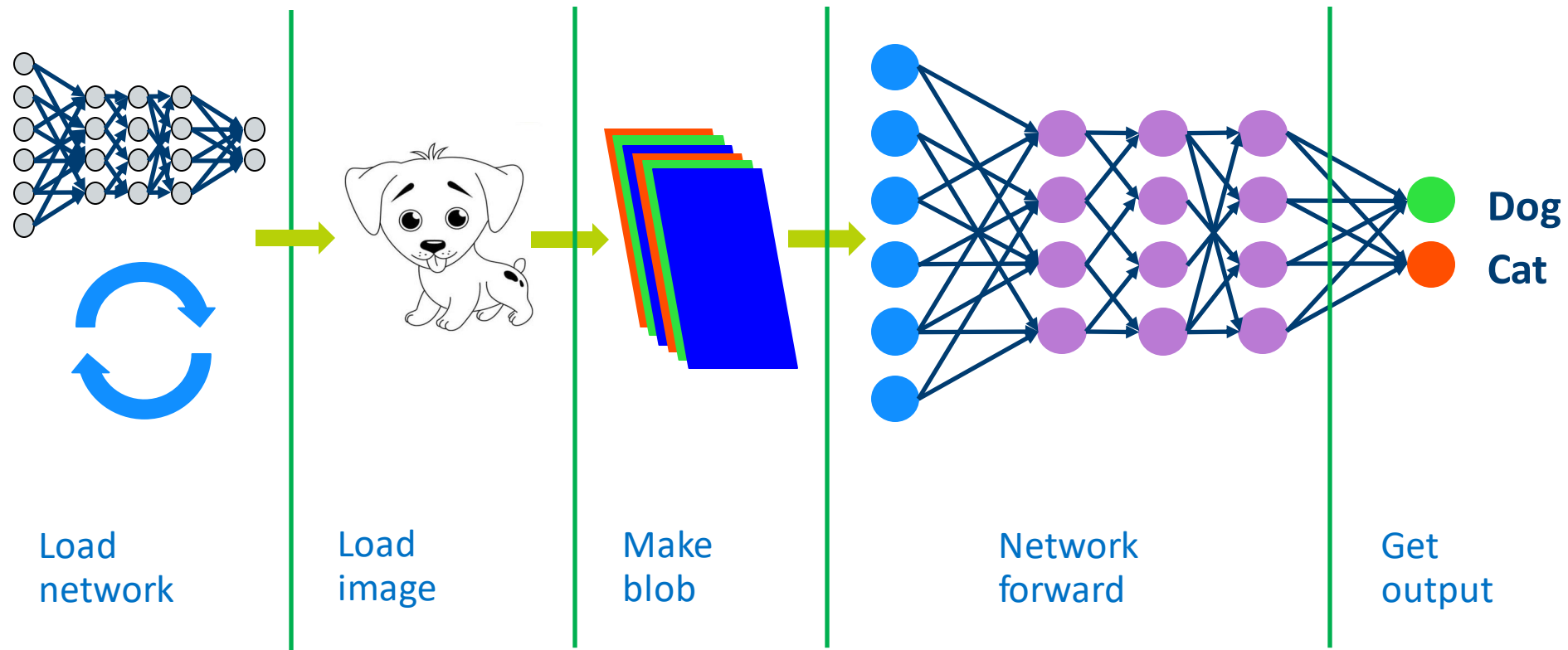
Inference



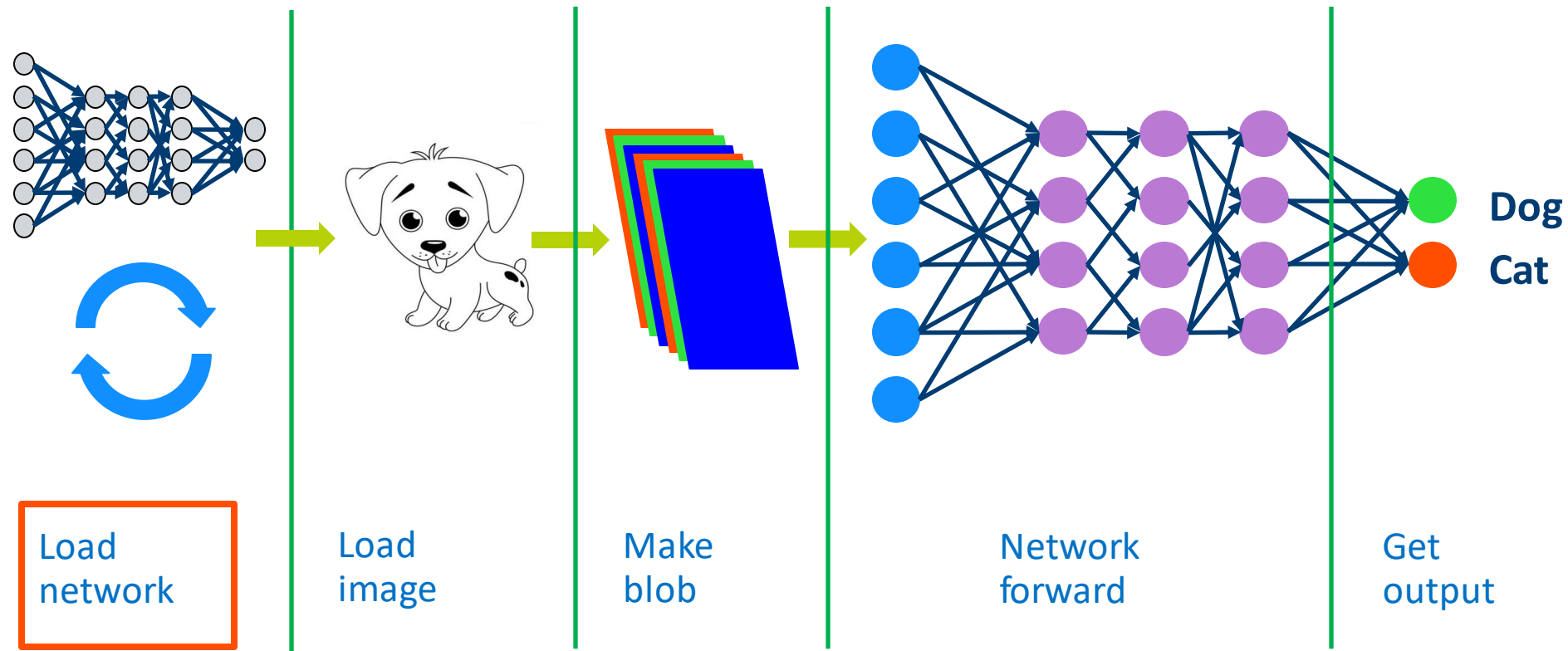
Deep neural network



Deep neural network

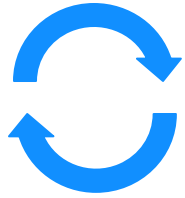
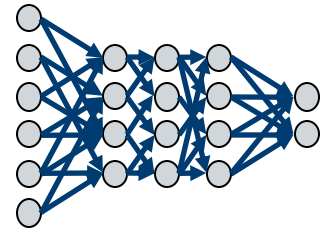


OpenCV DNN module



OpenCV DNN module

Load network

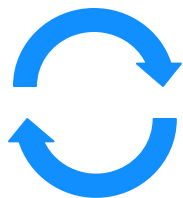
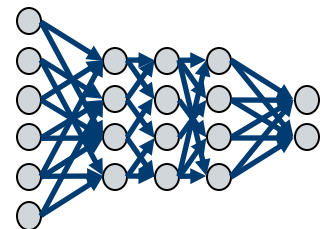


Load
network

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

OpenCV DNN module

Load network

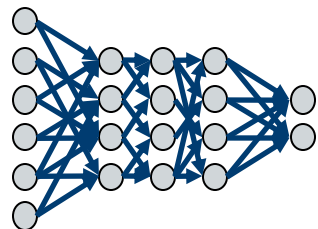


Load
network

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

OpenCV DNN module

Load network



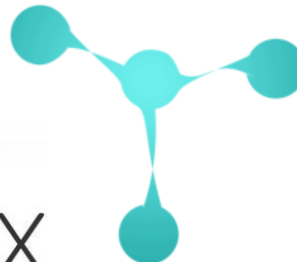
Load network

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

Caffe

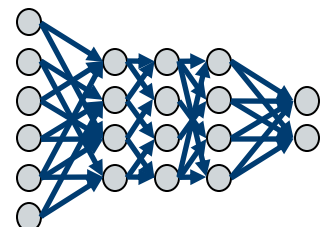


ONNX



OpenCV DNN module

Load network



Load network

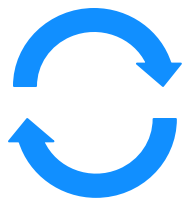
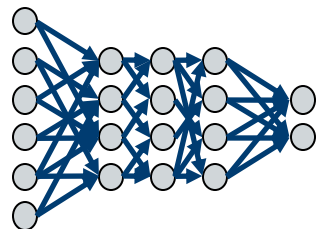
```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

Caffe



OpenCV DNN module

Load network



Load network

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

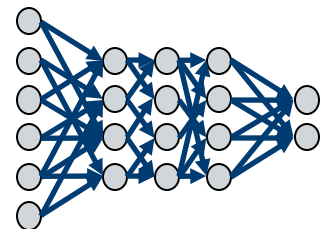
PYTORCH



ONNX

OpenCV DNN module

Load network

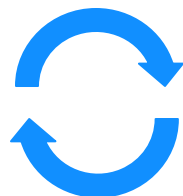
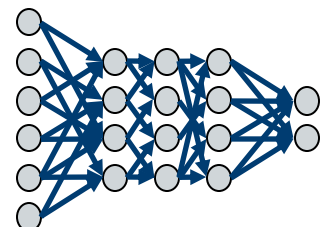


Load
network

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

OpenCV DNN module

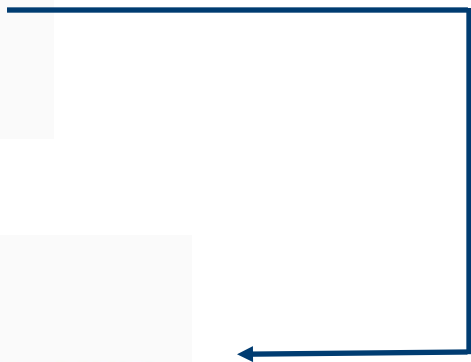
Load network



Load
network

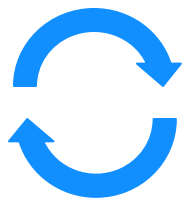
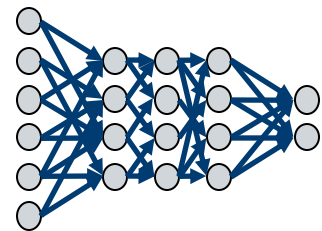
```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

```
int backendId = DNN_BACKEND_DEFAULT;  
int backendId = DNN_BACKEND_OPENCV;  
int backendId = DNN_BACKEND_INFERENCE_ENGINE;  
int backendId = DNN_BACKEND_HALIDE;
```



OpenCV DNN module

Load network



Load
network

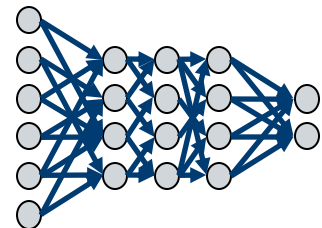


Halide

```
int backendId = DNN_BACKEND_DEFAULT;  
int backendId = DNN_BACKEND_OPENCV;  
int backendId = DNN_BACKEND_INFERENCE_ENGINE;  
int backendId = DNN_BACKEND_HALIDE;
```

OpenCV DNN module

Load network

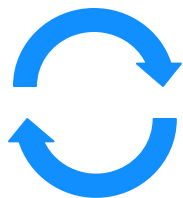
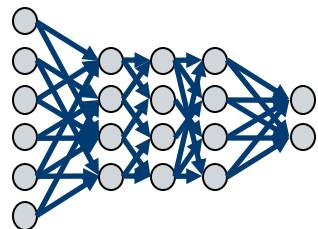


Load
network

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

OpenCV DNN module

Load network



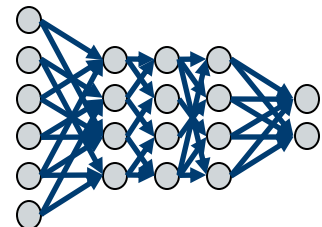
Load
network

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

```
int targetId = DNN_TARGET_CPU;  
int targetId = DNN_TARGET_OPENCL;  
int targetId = DNN_TARGET_OPENCL_FP16;  
int targetId = DNN_TARGET_MYRIAD;  
int targetId = DNN_TARGET_FPGA;
```

OpenCV DNN module

Load network



Load
network

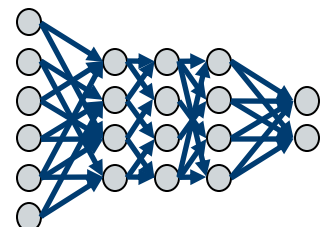
```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

```
int targetId = DNN_TARGET_CPU;  
int targetId = DNN_TARGET_OPENCL;  
int targetId = DNN_TARGET_OPENCL_FP16;  
int targetId = DNN_TARGET_MYRIAD;  
int targetId = DNN_TARGET_FPGA;
```



OpenCV DNN module

Load network



Load network

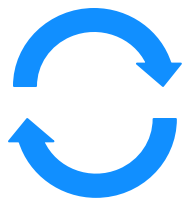
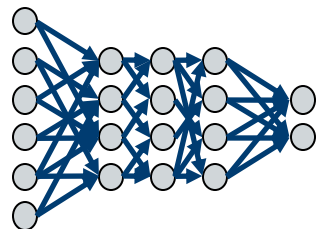
```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```



```
int targetId = DNN_TARGET_CPU;  
int targetId = DNN_TARGET_OPENCL;  
int targetId = DNN_TARGET_OPENCL_FP16;  
int targetId = DNN_TARGET_MYRIAD;  
int targetId = DNN_TARGET_FPGA;
```


OpenCV DNN module

Load network



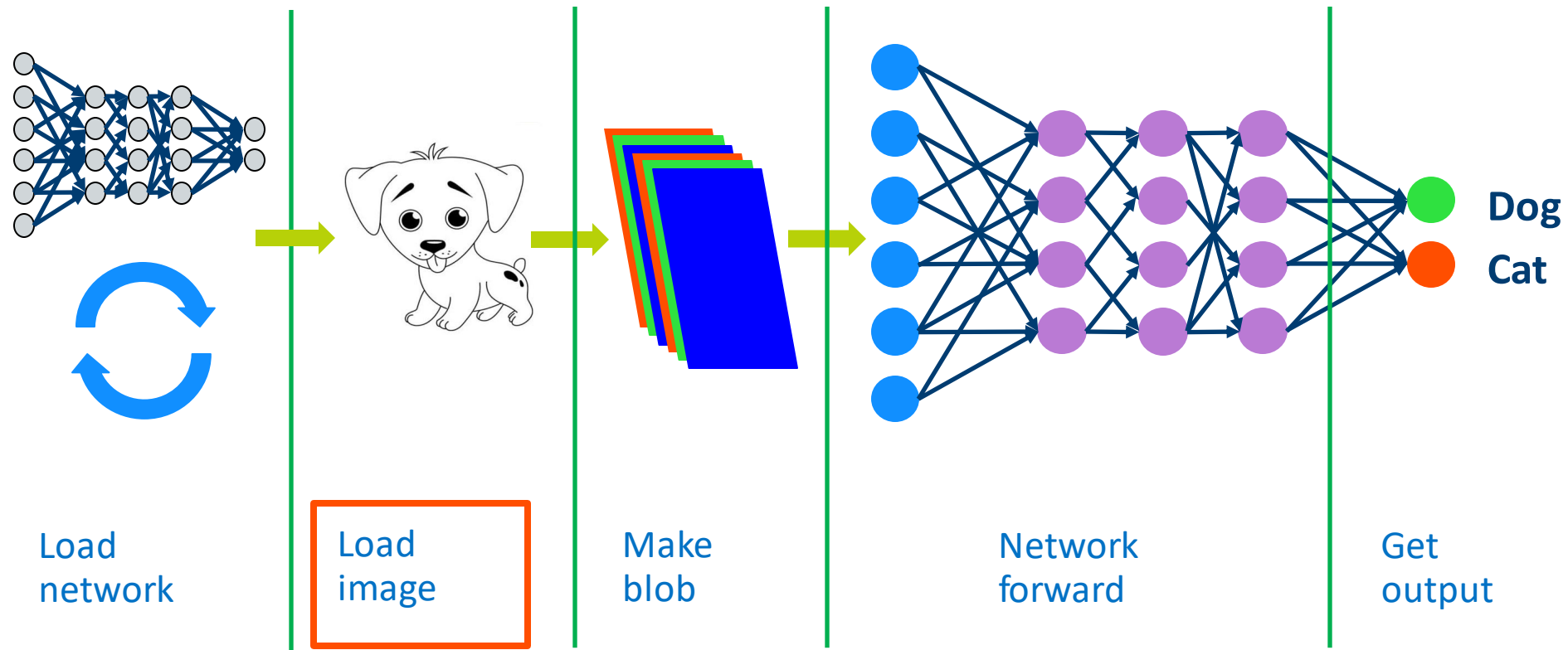
Load
network

Halide

```
Net net = readNet(model, config);  
net.setPreferableBackend(backendId);  
net.setPreferableTarget(targetId);
```

```
int targetId = DNN_TARGET_CPU;  
int targetId = DNN_TARGET_OPENCL;  
int targetId = DNN_TARGET_OPENCL_FP16;  
int targetId = DNN_TARGET_MYRIAD;  
int targetId = DNN_TARGET_FPGA;
```

OpenCV DNN module



OpenCV DNN module

Load image



Load
image

```
Mat frame = imread(path_image);
```

```
// comment
```

```
#include <opencv2/dnn.hpp>  
#include <opencv2/highgui.hpp>
```

```
using namespace cv;  
using namespace dnn;  
using namespace std;
```

OpenCV DNN module

Load image from video

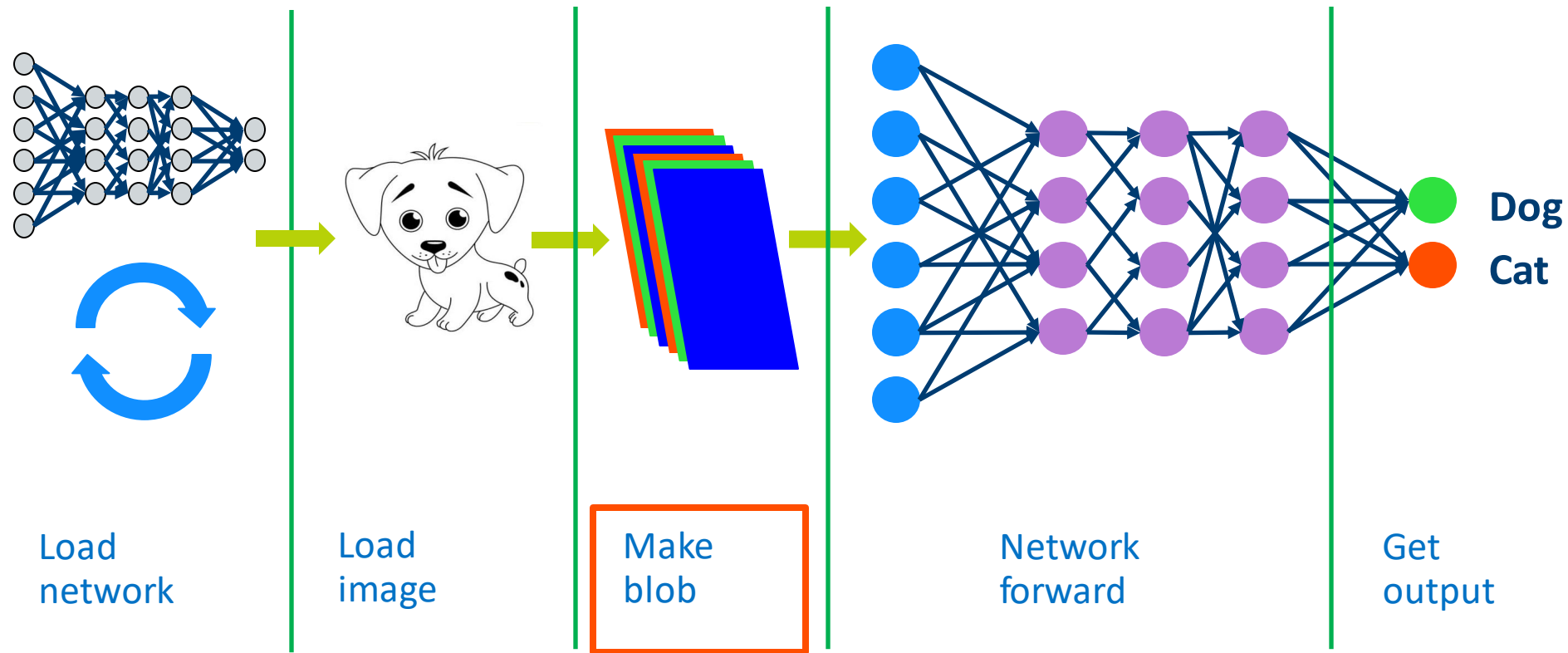


Load
image

```
Mat frame;
string win_name = "Deep learning in OpenCV";
namedWindow(win_name, WINDOW_NORMAL);

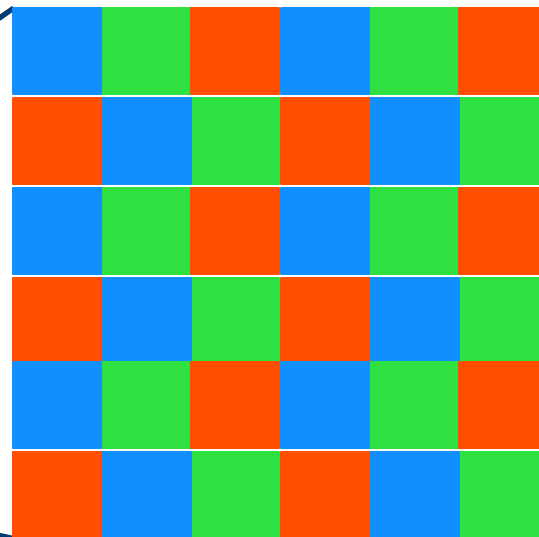
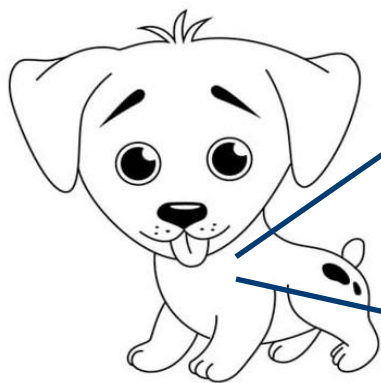
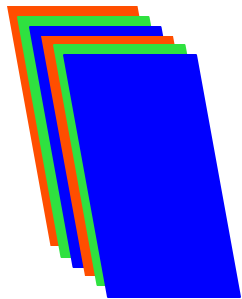
VideoCapture cap;
cap.open(0);
while (waitKey(1) < 0)
{
    cap >> frame;
    imshow(win_name, frame);
}
```

OpenCV DNN module



OpenCV DNN module

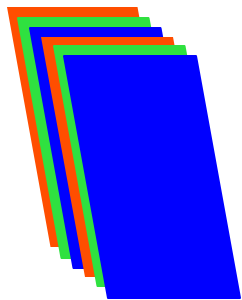
Make blob



Make
blob

OpenCV DNN module

Make blob

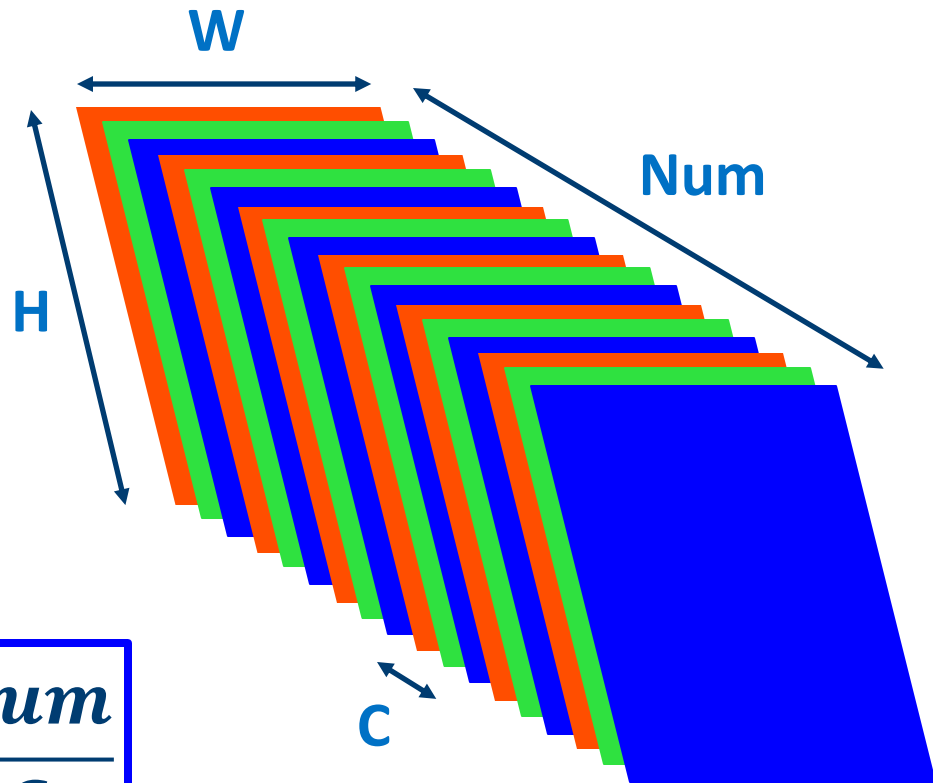


Make
blob



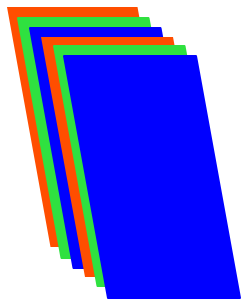
NCHW

$$N = \frac{Num}{C}$$

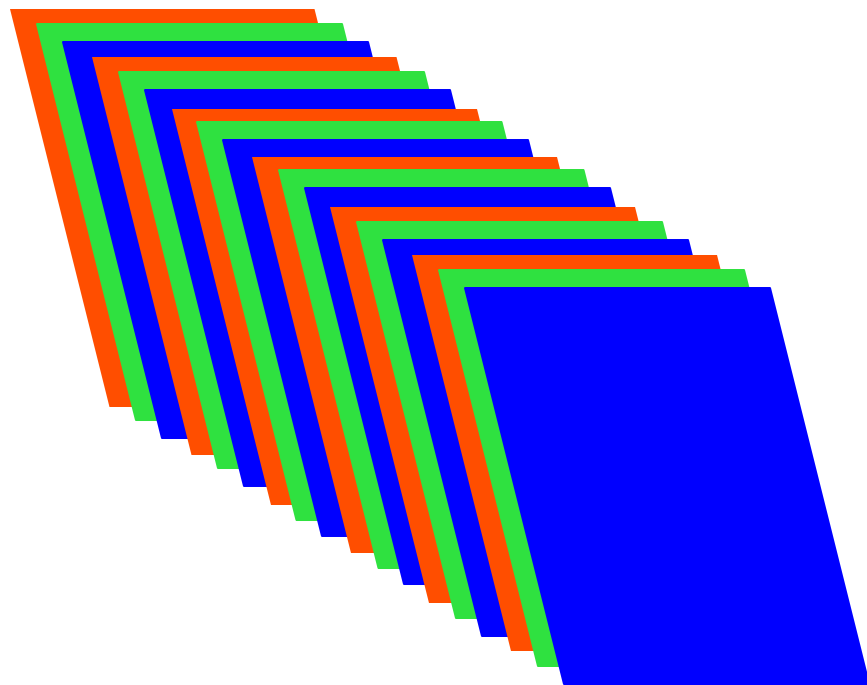


OpenCV DNN module

Make blob



NCHW



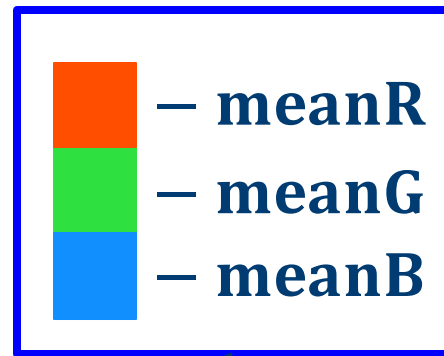
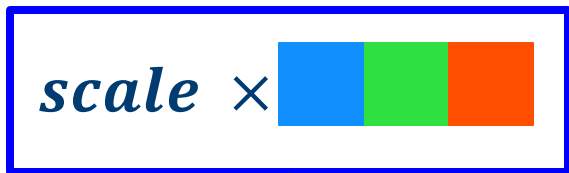
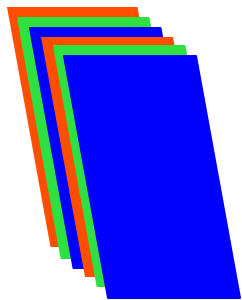
Make
blob

$[3 \times 128 \times 128]$

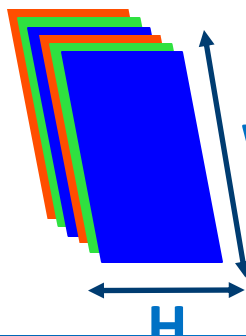
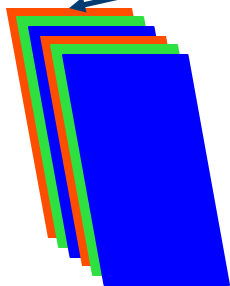
$[1 \times 3 \times 128 \times 128]$

OpenCV DNN module

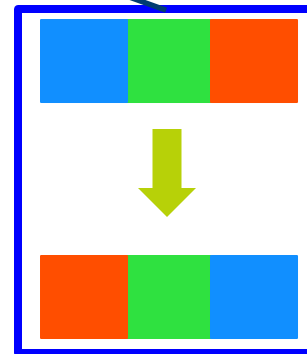
Make blob



```
blobFromImage(frame, blob, scale, spatial_size, mean, swapRB, crop, ddepth);
```

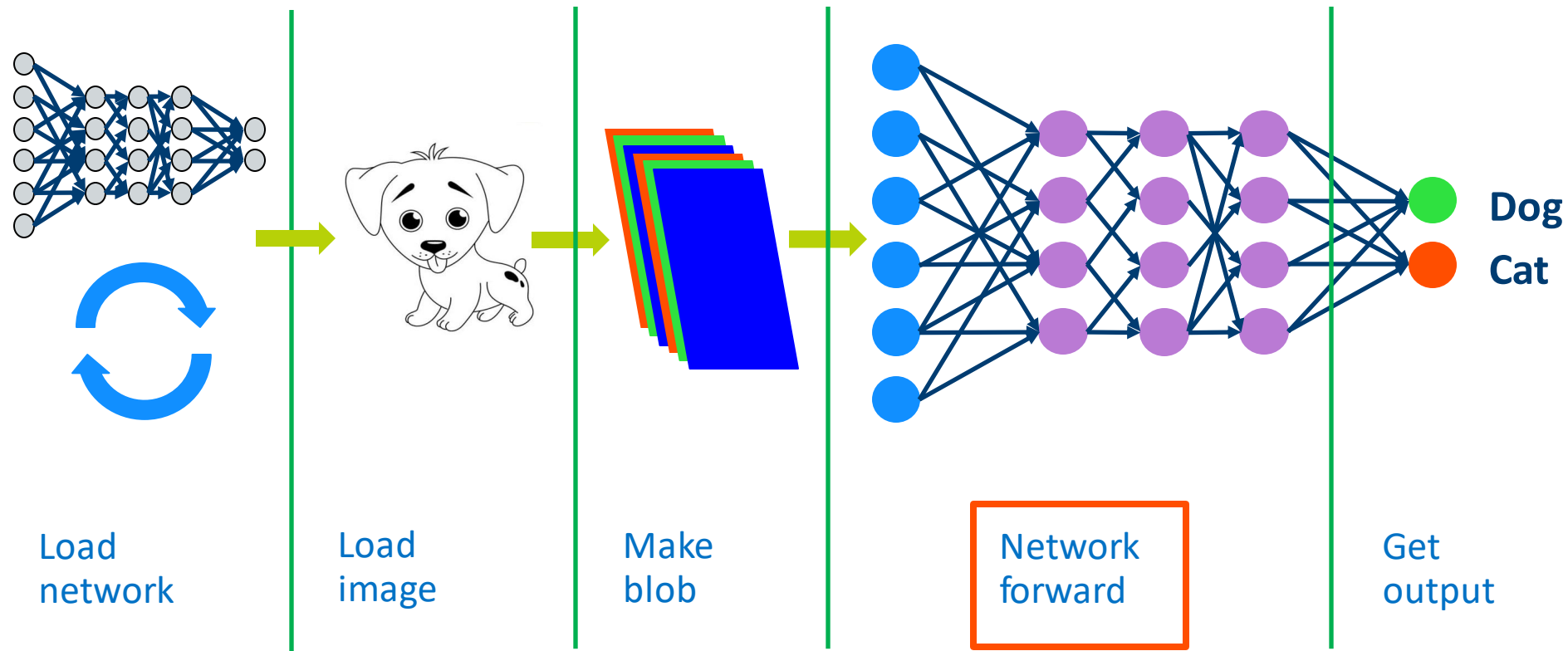


$W \rightarrow (H, W)$



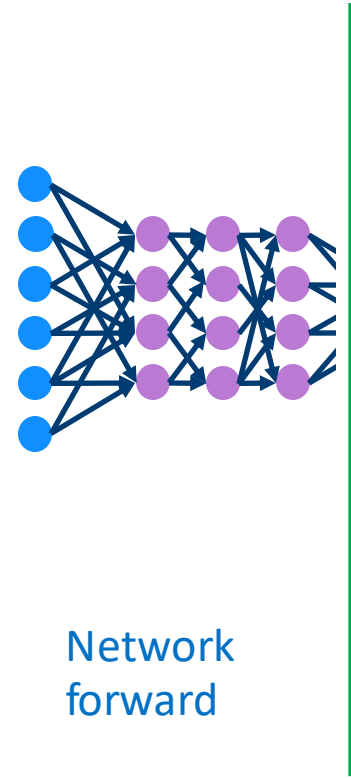
Make blob

OpenCV DNN module



OpenCV DNN module

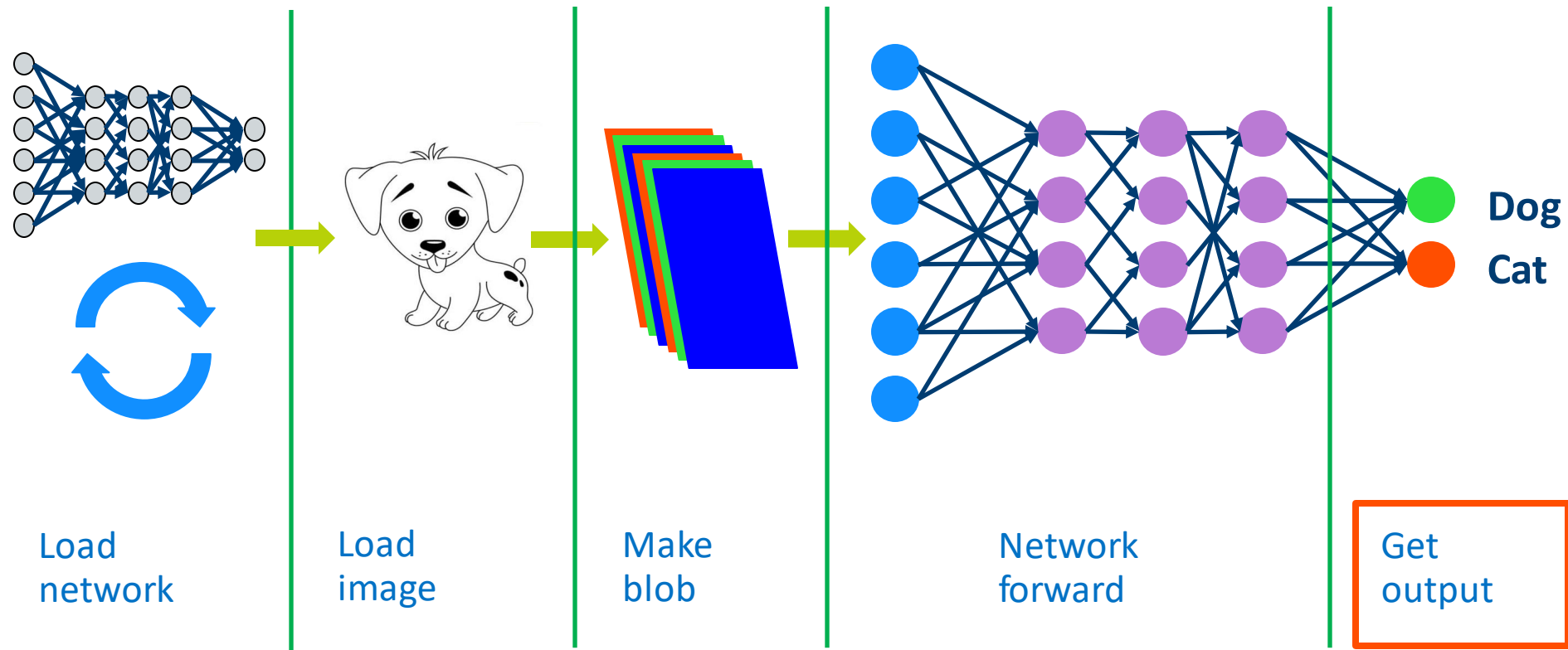
Network forward



```
net.setInput(blob);  
Mat prob = net.forward();
```

Network
forward

OpenCV DNN module



OpenCV DNN module

Get output for classification



```
Point classIdPoint;
double confidence;
minMaxLoc(prob.reshape(1, 1), 0, &confidence, 0, &classIdPoint);
int classId = classIdPoint.x;

cout << "Class: " << classId << '\n';
cout << "Confidence: " << confidence << '\n';
```

Get
output

